

## Project Partners



Department of Electronics, Information Science and Bioengineering  
Politecnico di Milano  
<http://www.biomed.polimi.it/nearlab>



Istituto di Tecnologie Industriali ed Automazione

Consiglio Nazionale delle Ricerche  
Istituto di Tecnologie Industriali ed Automazione  
<http://www.itia.cnr.it>



Imperial College of Science Technology and Medicine  
Department of Mechanical Engineering  
<http://www3.imperial.ac.uk/mechatronicsinmedicine>



Karlsruher Institut fuer Technologie  
Institute for Process Control and Robotics (IPR)  
<http://wwwipr.ira.uka.de/>



Fondazione Istituto Italiano di Tecnologia  
Department Advanced Robotics (ADVR)  
<http://www.iit.it/en/advanced-robotics.html>



TECHNION - Israel Institute of Technology  
Faculty of Mechanical Engineering  
<http://robotics.technion.ac.il/>



Technische Universität München,  
Lehrstuhl für Computeranwendungen in der Medizin,  
Institut für Informatik  
<http://campar.in.tum.de/Chair/ResearchGroupCamp>



German Research Centre for Artificial Intelligence GmbH

Deutsches Forschungszentrum für Künstliche Intelligenz GMBH - <http://www.dfki.de>



Dipartimento Tecnico scientifico Interaziendale Milanese di Diagnostica Epilettologica Pre-chirurgica



The Foundation for Medical Research Infrastructural Development and Health Services next to the Medical Center Tel Aviv  
Tel- Aviv Sourasky Medical Center - Functional Brain Center



Force Dimension  
<http://www.forcedimension.com/>



Renishaw (Ireland) Ltd - <http://www.renishaw.com>



MediMaton Limited - <http://www.medimaton.com>



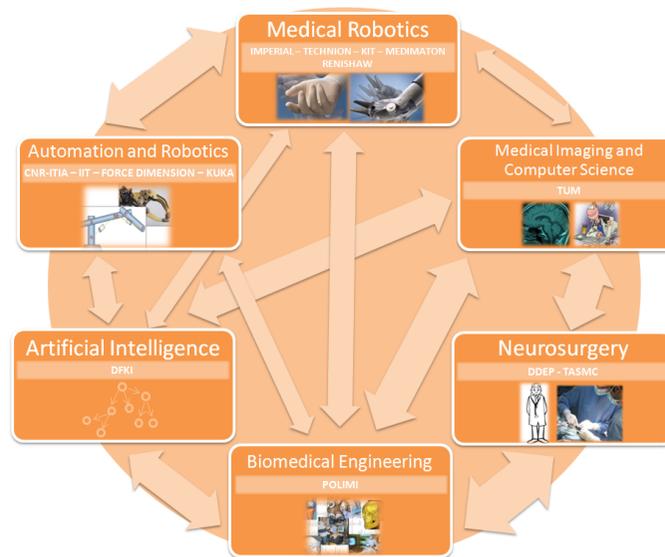
CF consulting - Finanziamenti Unione Europea s.r.l.  
<http://www.cf-consulting.it/>



KUKA Laboratories GMBH  
<http://www.kuka.com>



[www.active-fp7.eu](http://www.active-fp7.eu)



## Information and Communication Technologies

Cognitive Systems and Robotics (ICT-2009.2.1)  
FP7-ICT-2009-6  
Ref: 270460



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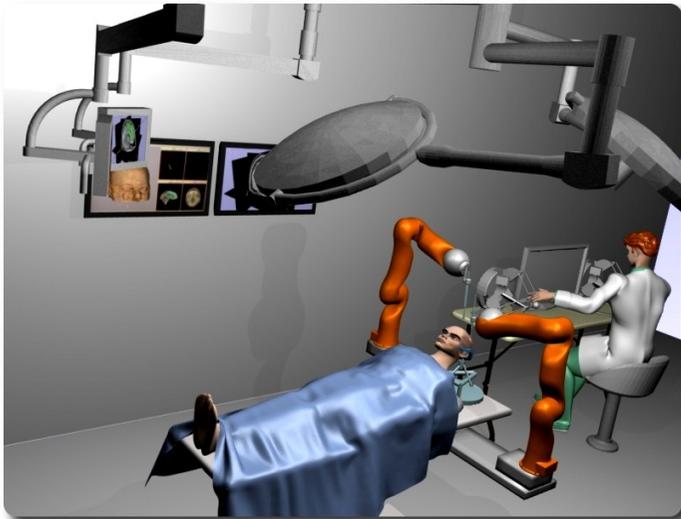
## The Project



The ACTIVE project exploits ICT and other engineering methods and technologies for **the design and development of an integrated multi-robotic platform for neurosurgery.**

A light and agile robotic cell with 20 degrees-of-freedom (DoFs) and an advanced processing unit for pre- and intra-operative control will operate both autonomously and cooperatively with surgical staff on the brain, a loosely structured environment.

As the patient will not be considered rigidly fixed to the operating table and/or to the robot, the system will push the boundaries of the state of the art in the fields of robotics and control for the accuracy and bandwidth required by the challenging and complex surgical scenario.



## The Goal

The ACTIVE project outcome will be a novel robotic suite for awake patient surgery.

**Three cooperating robots will interact with the brain** that will deform for the tool contact, blood pressure, breathing and deliquoration.

**Human factors** are considered by allowing easy interaction with the users through a novel haptic interface for tele-manipulation and by a collaborative control mode.

**Active constraints** will limit and direct tool tip position, force and speed preventing damage to eloquent areas, defined on realistic tissue models updated on-the-field through sensors information. The active constraints will be updated (displaced) in real time in response to the feedback from tool-tissue interactions and any additional constraints arising from a complex shared workspace.

**The operative room represents the epitome of a dynamic and unstructured volatile environment**, crowded with people and instruments. The workspace will be monitored by environmental cameras, and machine learning techniques will be used for the safe workspace sharing. Decisions about collision avoidance and downgrading to a safe state will be taken autonomously, the movement of the head of the patient will be filtered by a bespoke active head frame, while fast and unpredictable patient motion will be compensated by a real-time cooperative control system. Cognitive skills will help to identify the target location in the brain and constrain robotic motions by means of on-field observations.



## The Impact

Cognitive researches within ACTIVE, aimed at robotic behavior customization, provide scientific and technological impact in the field of adaptive robotic control, by improving system control strategy through experience and on-field learning.

The quality of surgical robots will be increased since the surgeon will be able to perform brain surgeries (for epilepsy in the primary scenario, with possible follow-up in DBS and tumors removal) with **awake patient**. This is crucial in order to better identify eloquent areas to preserve during tissue removal. The potential number of patients for epilepsy surgery is approximately 10.000 to 24.000 patients per year in Europe.

The ACTIVE project is aimed at strengthen professional service robotics market in Europe, allowing its possible exploiter RENISHAW to position its Neurological department in the world market. FORCE DIMENSION and KUKA will act as provider of robotic components for OEMs which integrate these components into their medical systems.

