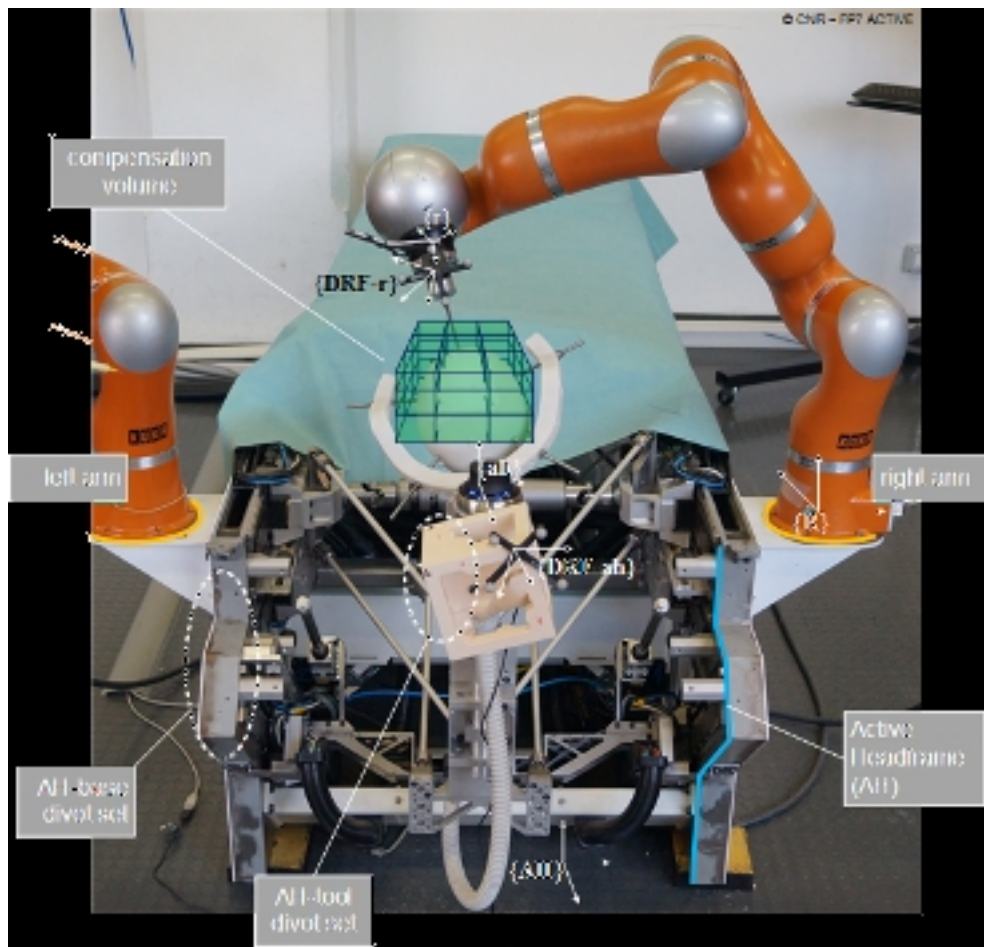


Motion compensation: accuracy

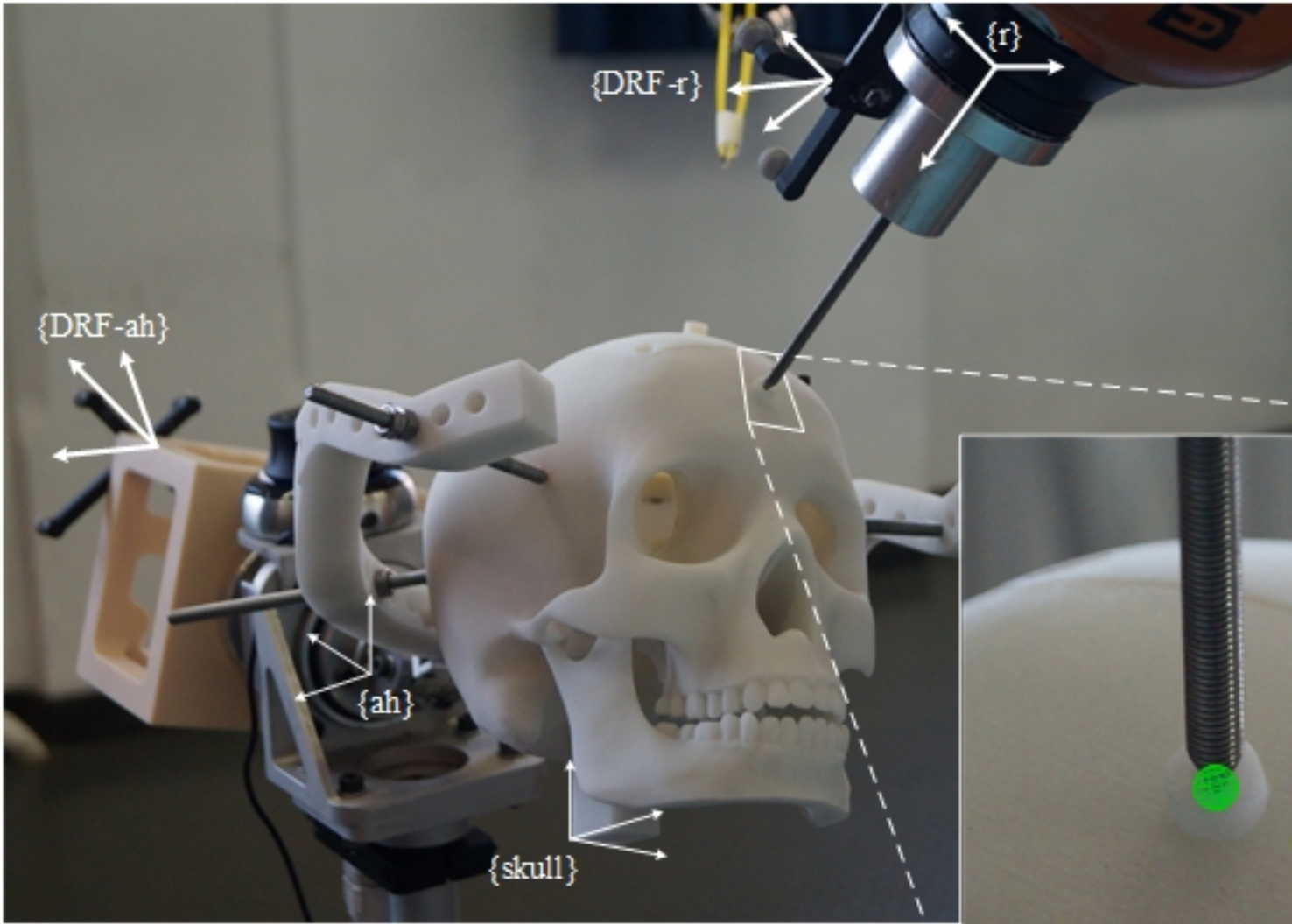
ACTIVE multirobot platform is dedicated to the coordinated motion of the master Active Headframe



The multi-robot system has multiple sources of kinematical inaccuracies, i.e. intrinsic calibration of robot

Results - Motion Compensation

Last Updated Friday, 13 February 2015 17:46



The procedure developed at USC in 2004 helps to solve the problem of the current skull drilling guide (based on a simple